

# Observations for NWP

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# Outline

- Background
- System aspects

# Background

- Observations in NWP
- Global observing system
  - Conventional observations (GTS)
  - Satellite observations (EUMETCast)
  - Radar observations (OPERA/ODYSSEY)
  - Other observations



# Acknowledgments

- Previous ECMWF DA training courses
  - <https://confluence.ecmwf.int/display/OPTR/Our+training+resources>
- 2014 HIRLAM training course
  - <https://hirlam.org/trac/wiki/HarmonieSystemTraining2014/Programme>
- The internet!

# Observations in NWP

# The observing system

- 1700s: Short lived networks (GB, FR, RUS, ...)
- 1800s: Better instrumentation and telegraph
- 1854: Storm destroys French fleet at Balaklava
- 1855: France set up observing network
- 1873: International Meteorological Conference of Vienna placed cooperation on a formal diplomatic basis. (Permanent international committee established soon after)
- 1950: Good upper-air network over land (NH)
- 1963: WMO World Weather Watch
- 1979: Global Weather Experiment



# Observations in NWP

- Initial value problem
- Minimise a cost function (3D-Var):

$$J(x) = (x - x_b)B^{-1}(x - x_b) + (\mathbf{y} - H[x])R^{-1}(\mathbf{y} - H[x])$$

- Fill observation vector,  $\mathbf{y}$ , with good-quality observations of atmosphere

# Global observing system

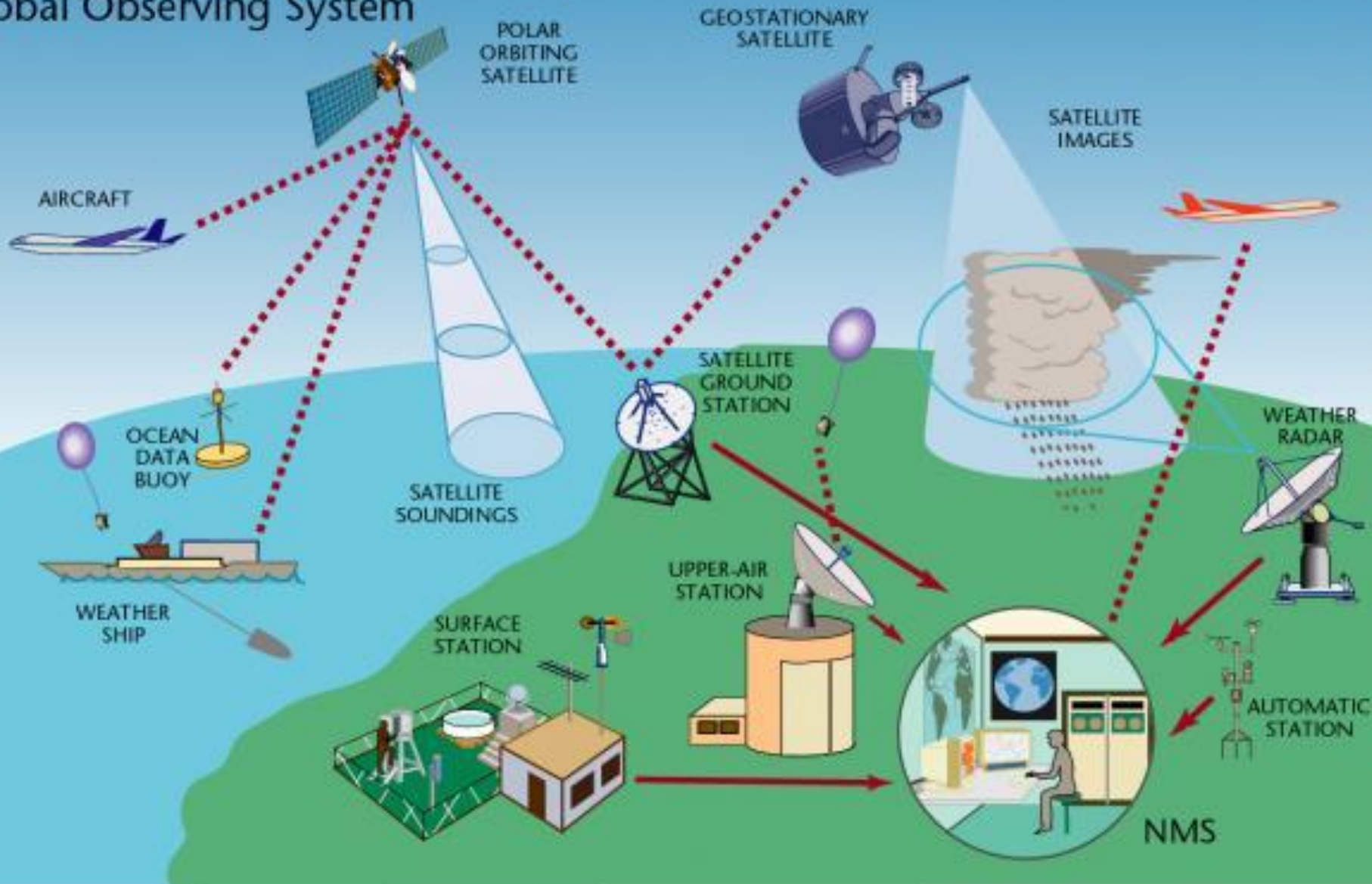


# Global Observing System

- WMO programme
  - <https://public.wmo.int/en/programmes/global-observing-system>
- Surface, Upper-air, Marine, Aircraft, Satellite, Radar, Other

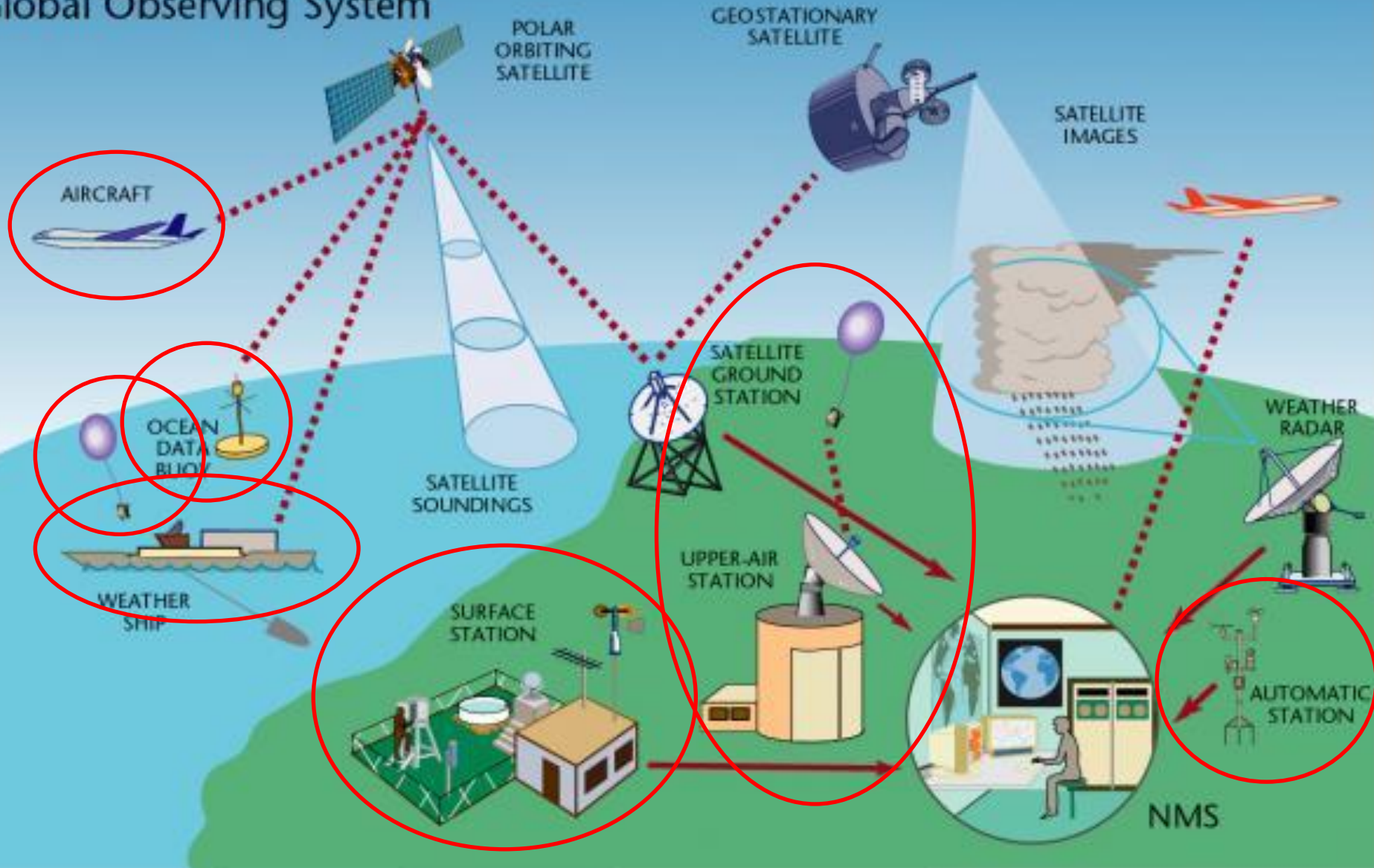
*Offering operationally reliable, surface-based and space-based subsystems with observing facilities on land, at sea, in the air and in outer space in support of the World Weather Watch and climate applications.*

# Global Observing System



Credit: WMO, <https://public.wmo.int/en/programmes/global-observing-system>

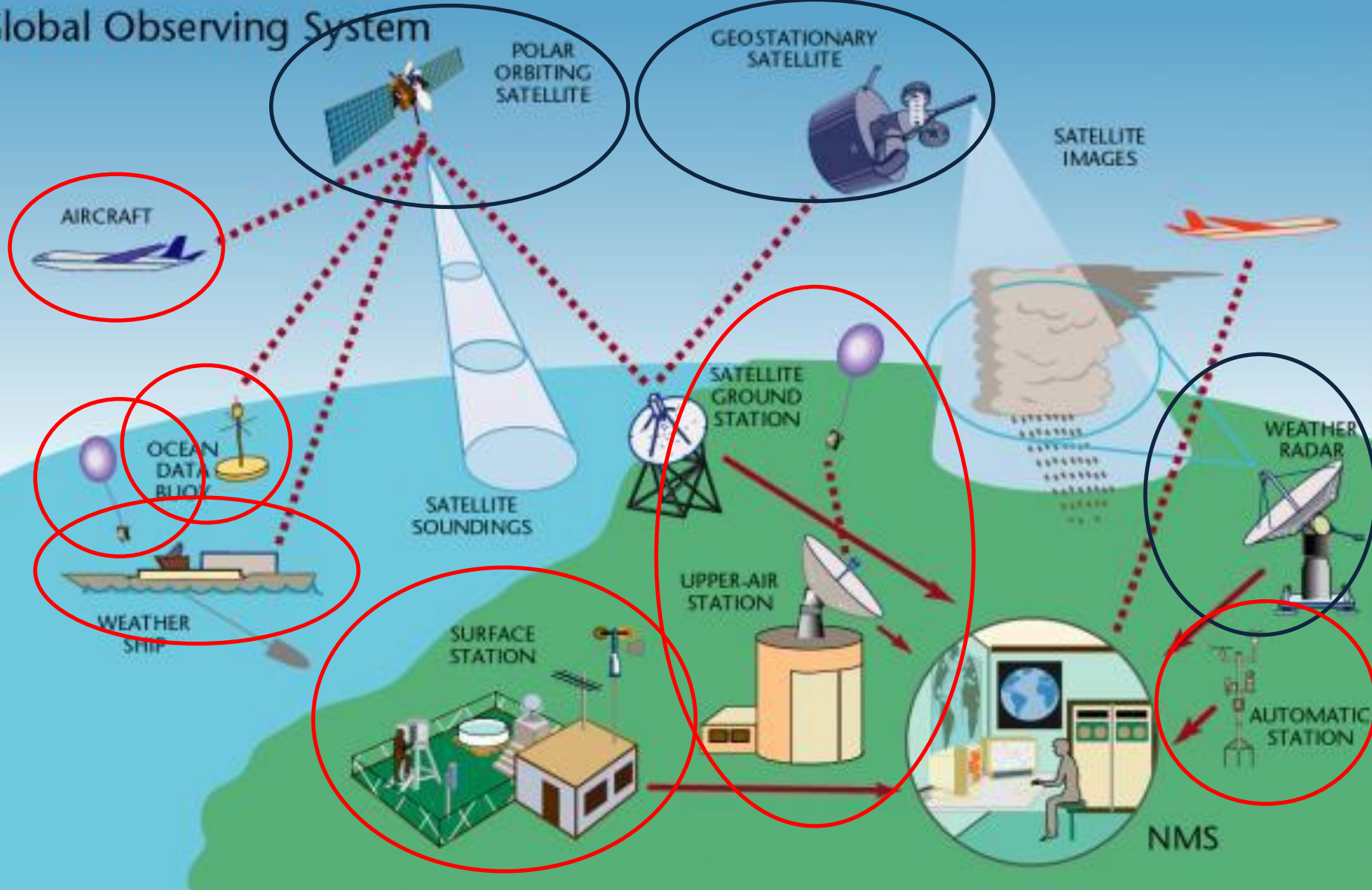
# Global Observing System



Credit: WMO, <https://public.wmo.int/en/programmes/global-observing-system>



# Global Observing System



Credit: WMO, <https://public.wmo.int/en/programmes/global-observing-system>

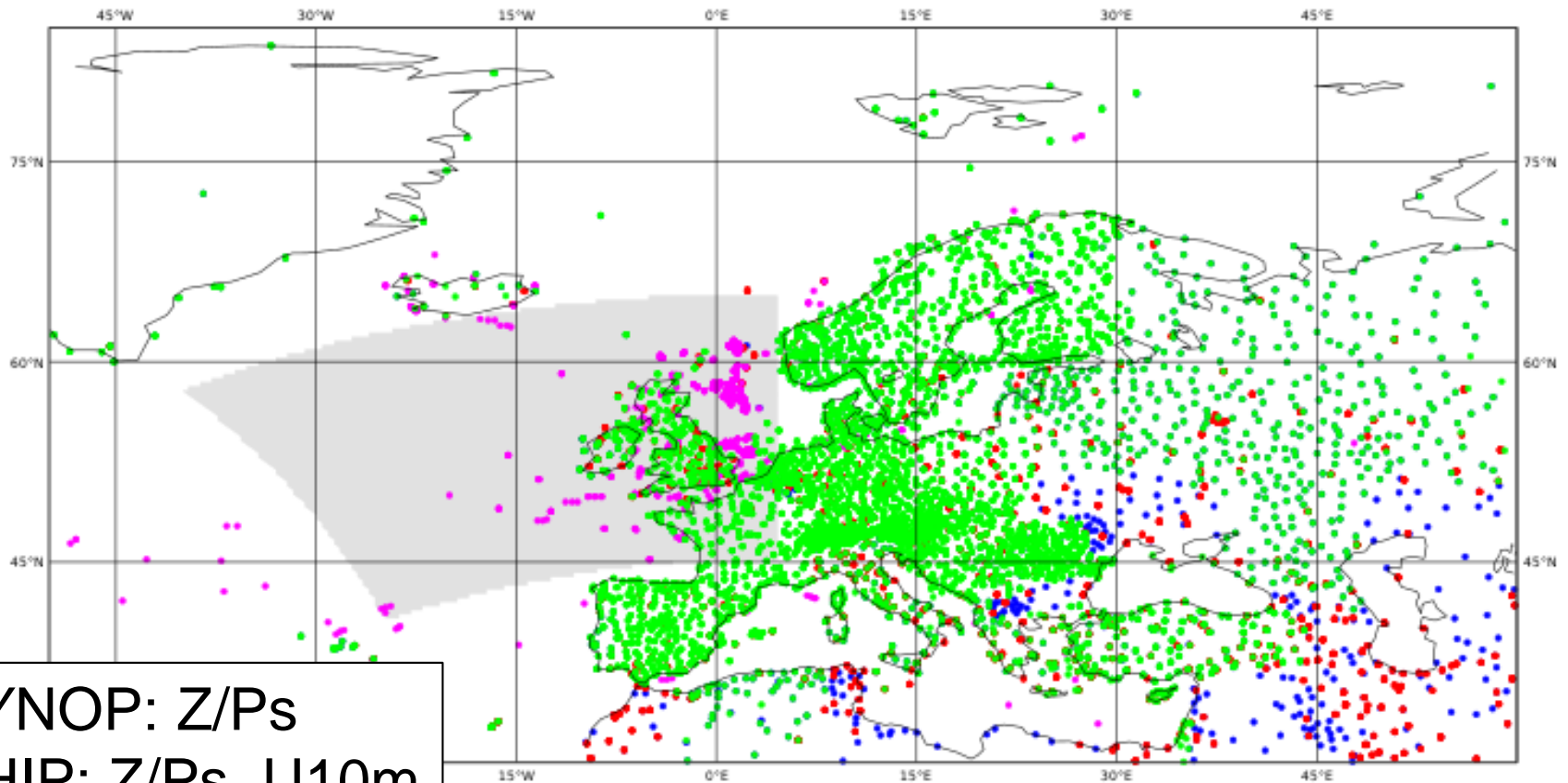


# Data Coverage: SYNOP-SHIP-METAR

2019-01-28: 12 UTC +/- 90min

Total number of observations: 14589

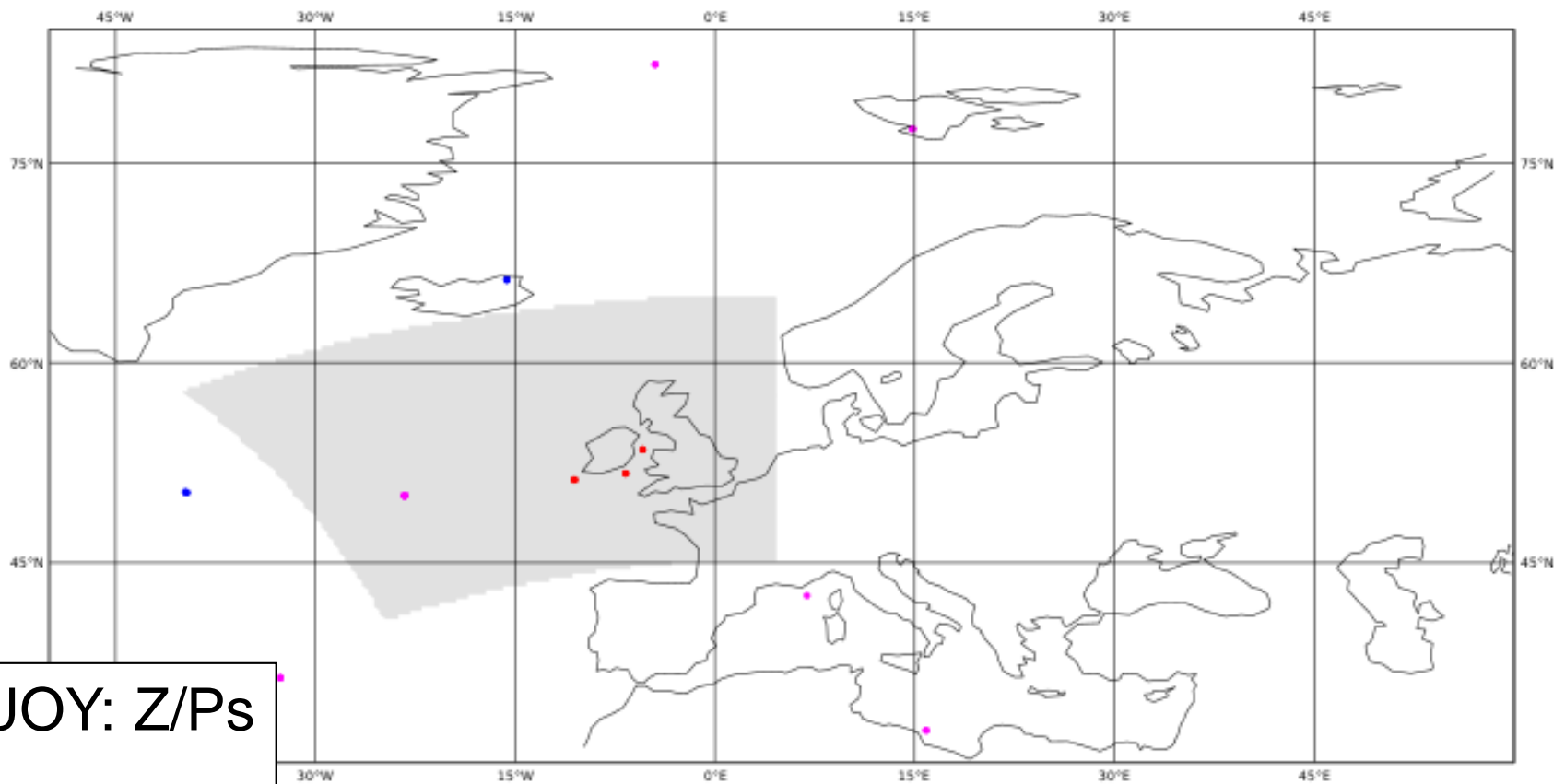
- SYNOP-Land TAC: 2040
- METAR: 3947
- SHIP TAC: 678
- METAR-AUTO: 0
- SYNOP-Ship BUFR: 0
- SYNOP-Land BUFR: 7924



SYNOP: Z/Ps  
SHIP: Z/Ps, U10m

Data Coverage: BUOY  
2019-01-28: 12 UTC +/- 90min  
Total number of observations: 46

- DRIFTER: 6
- TESAC: 0
- MOORED BUOY BUFR: 9
- DRIFTER BUOY BUFR: 31
- BATHY: 0

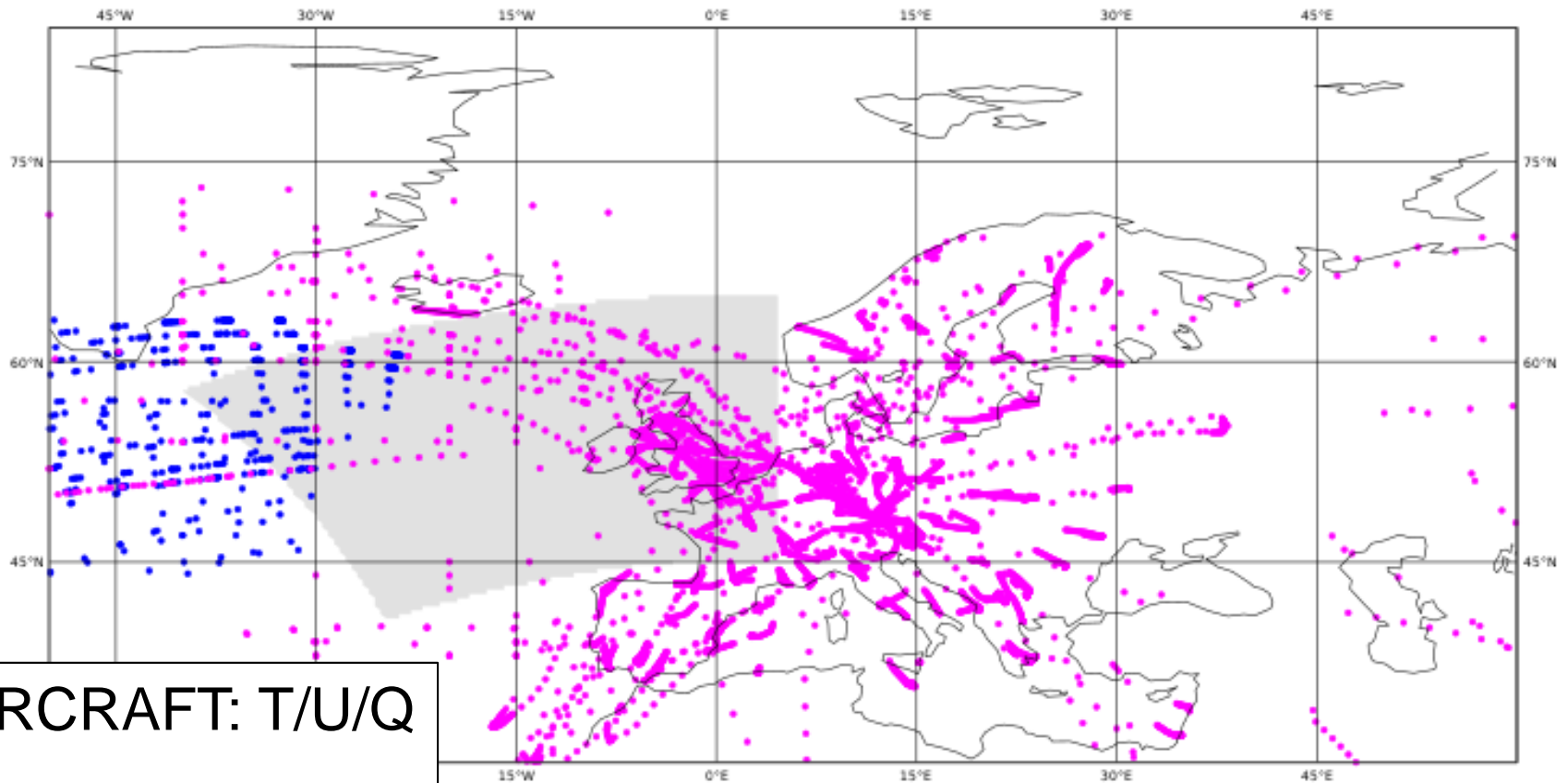


BUOY: Z/Ps



Data Coverage: AIRCRAFT  
2019-01-28: 12 UTC +/- 90min  
Total number of observations: 8617

- AIREP: 457
- AMDAR: 0
- WIGOS AMDAR: 8160

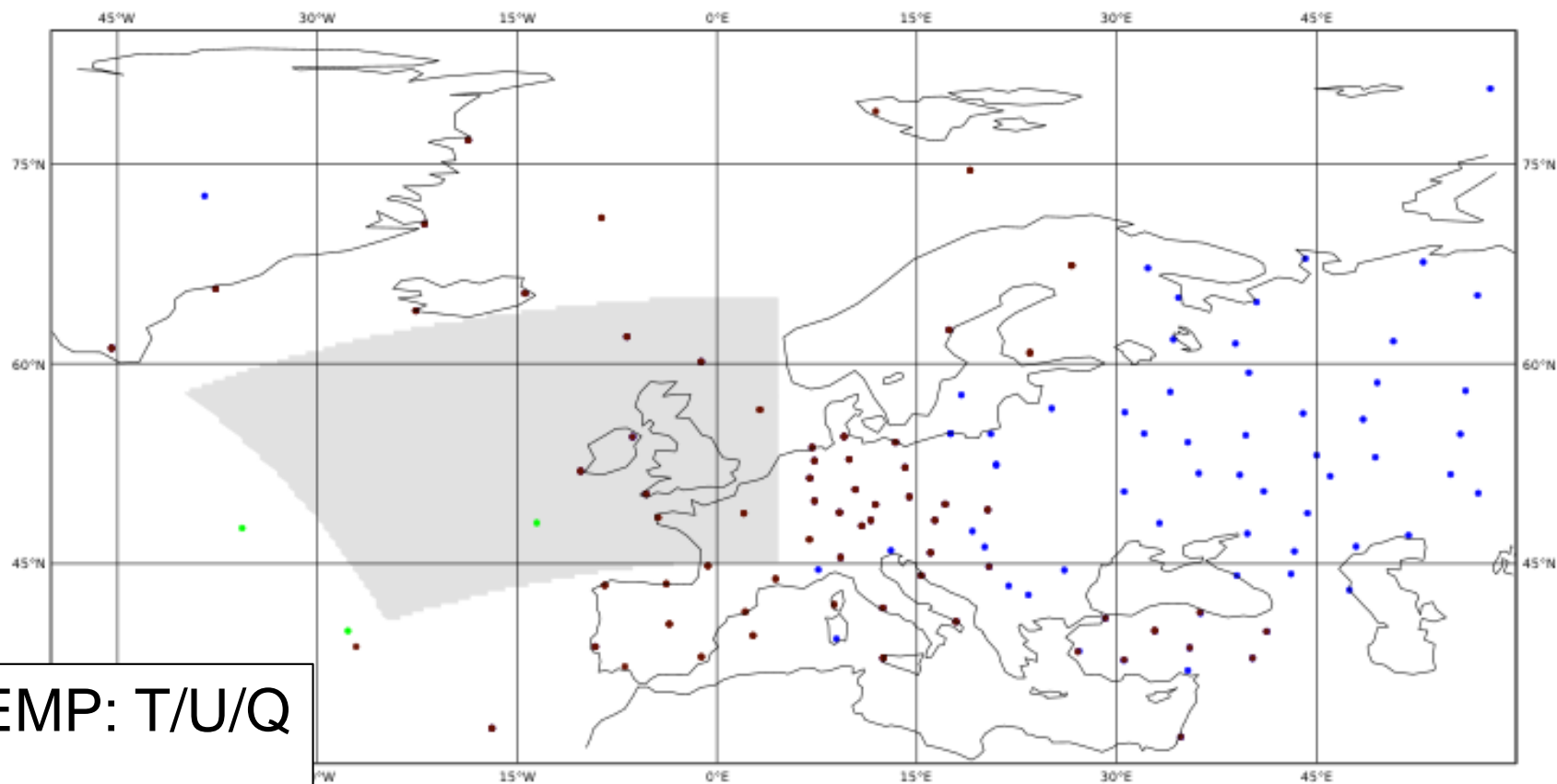


AIRCRAFT: T/U/Q



Data Coverage: **RADIOSONDE**  
2019-01-28: 12 UTC +/- 90min  
Total number of observations: 232

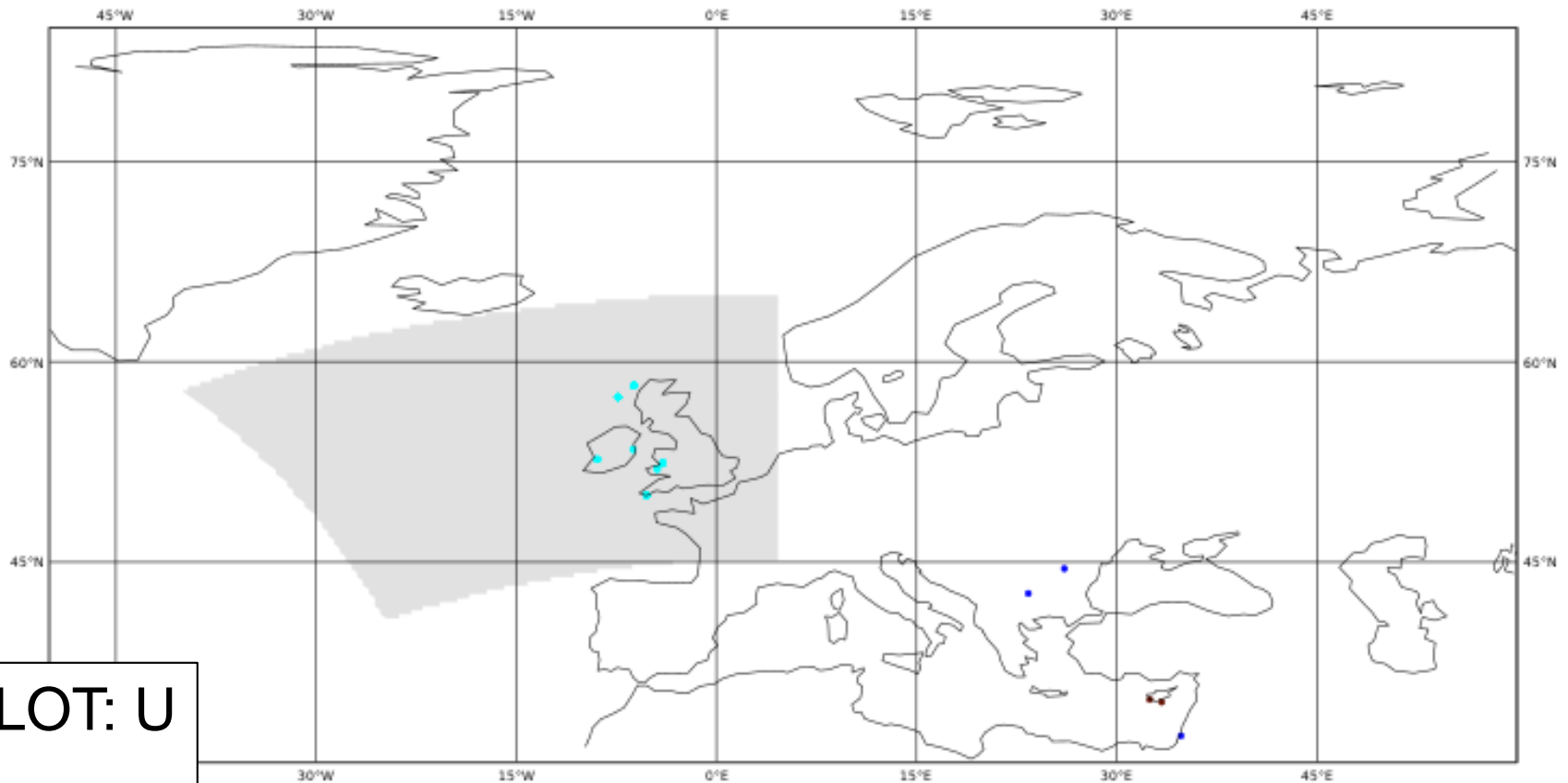
- TEMP-Land TAC: 104
- TEMP-Ship TAC: 0
- TEMP-Drop: 0
- TEMP-Mobile: 0
- BUFR TEMP-Land: 125
- BUFR TEMP-Ship: 3



# Data Coverage: PILOT-PROFILER

2019-01-28: 12 UTC +/- 90min  
Total number of observations: 85

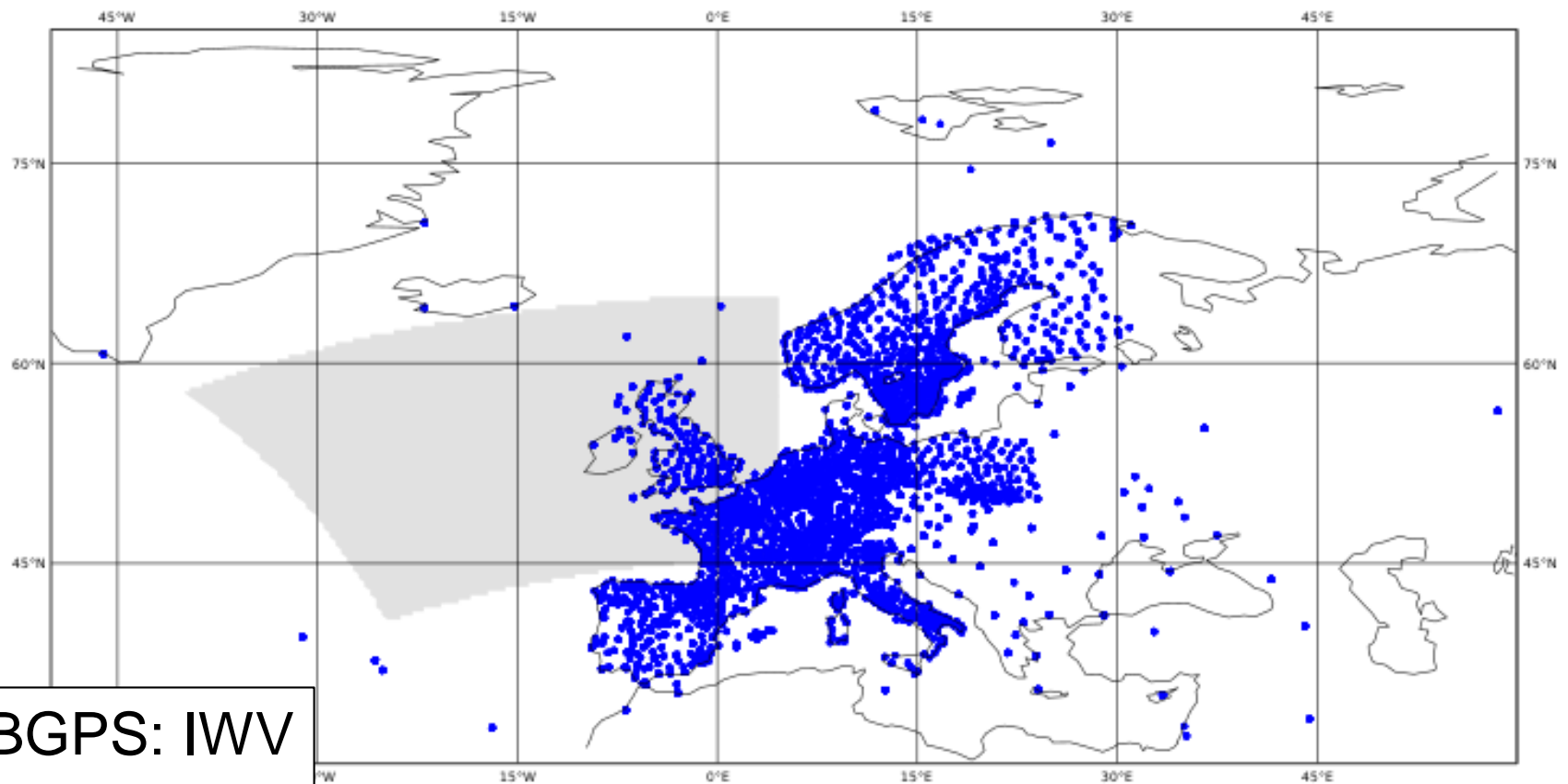
- PILOT LAND: 3
- PILOT SHIP: 0
- US WIND PROF.: 0
- EURO WIND PROF.: 80
- BUFR LAND PILOT: 2
- BUFR SHIP PILOT: 0



PILOT: U

Data Coverage: GROUND-BASED GPS  
2019-01-28: 12 UTC +/- 90min  
Total number of observations: 42364

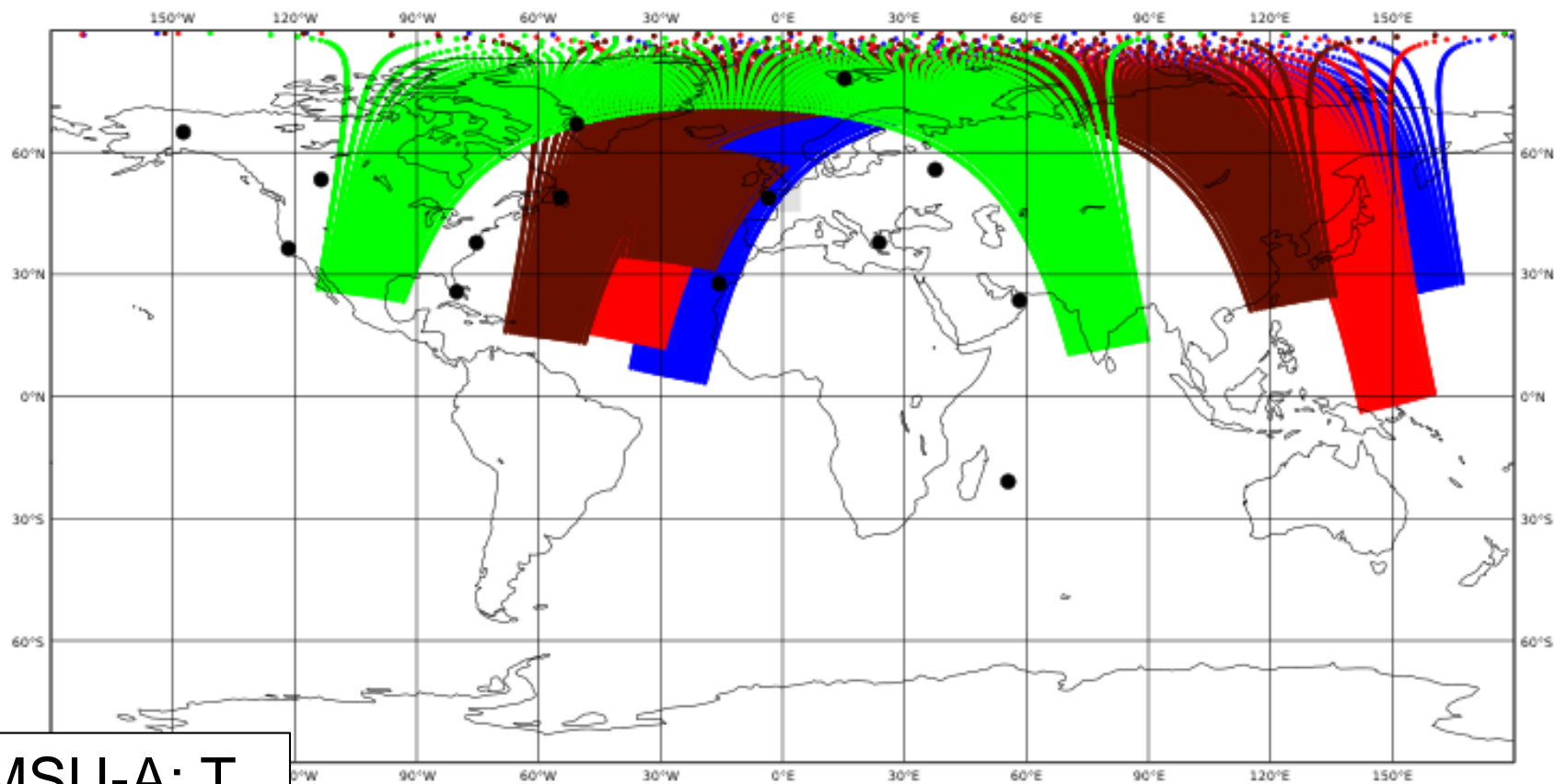
- GBGPS: 42364



**GBGPS: IWV**

Data Coverage: AMSU-A  
2019-01-24: 12UTC +/-90min  
Total number of observations: 62460

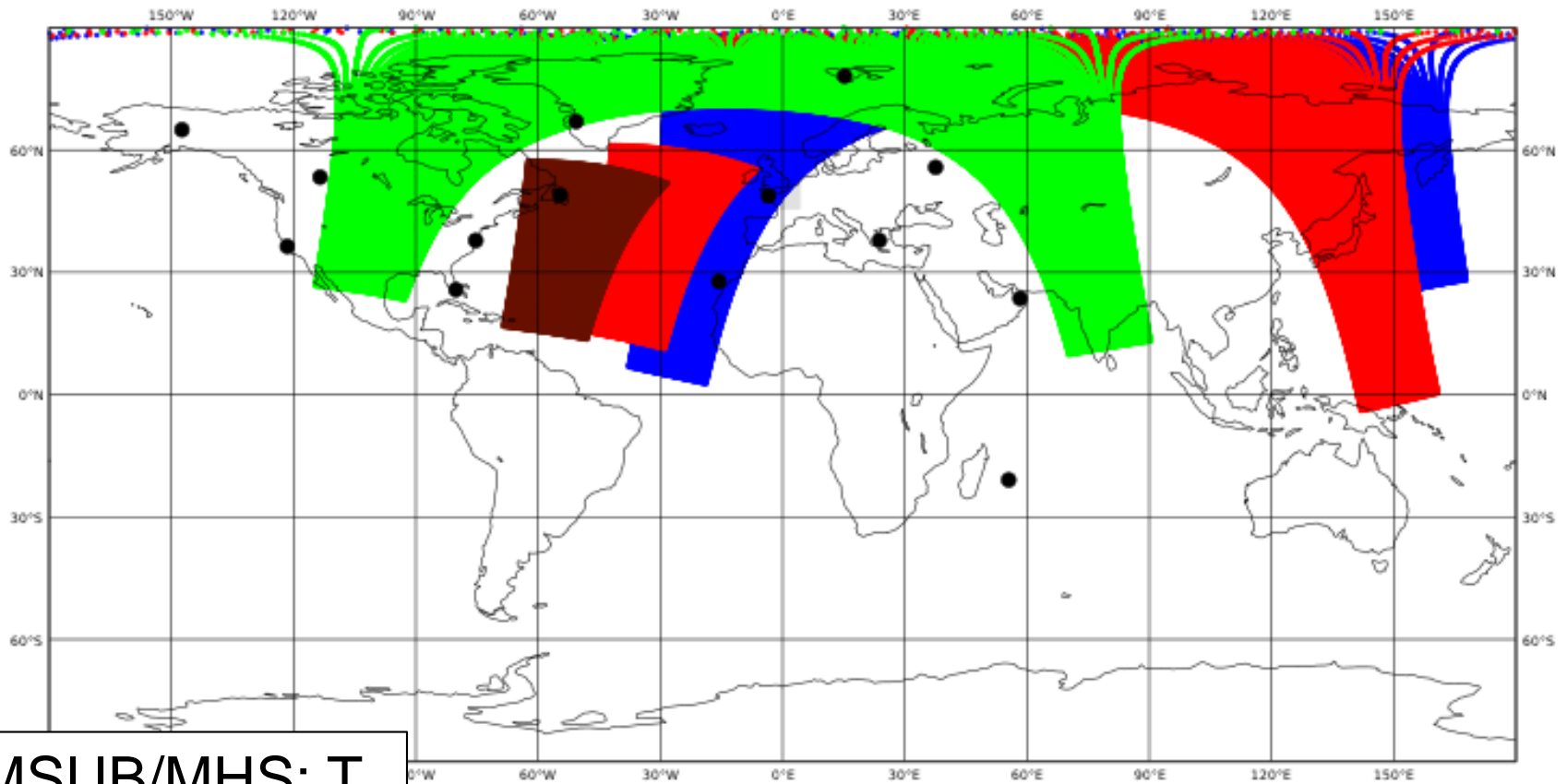
- METOP-A: 14850
- METOP-B: 10320
- NOAA-18: 17790
- NOAA-19: 19500
- NOAA-20: 0



AMSU-A:  $T_b$

Data Coverage: AMSU-B/MHS  
2019-01-24: 12UTC +/-90min  
Total number of observations: 425430

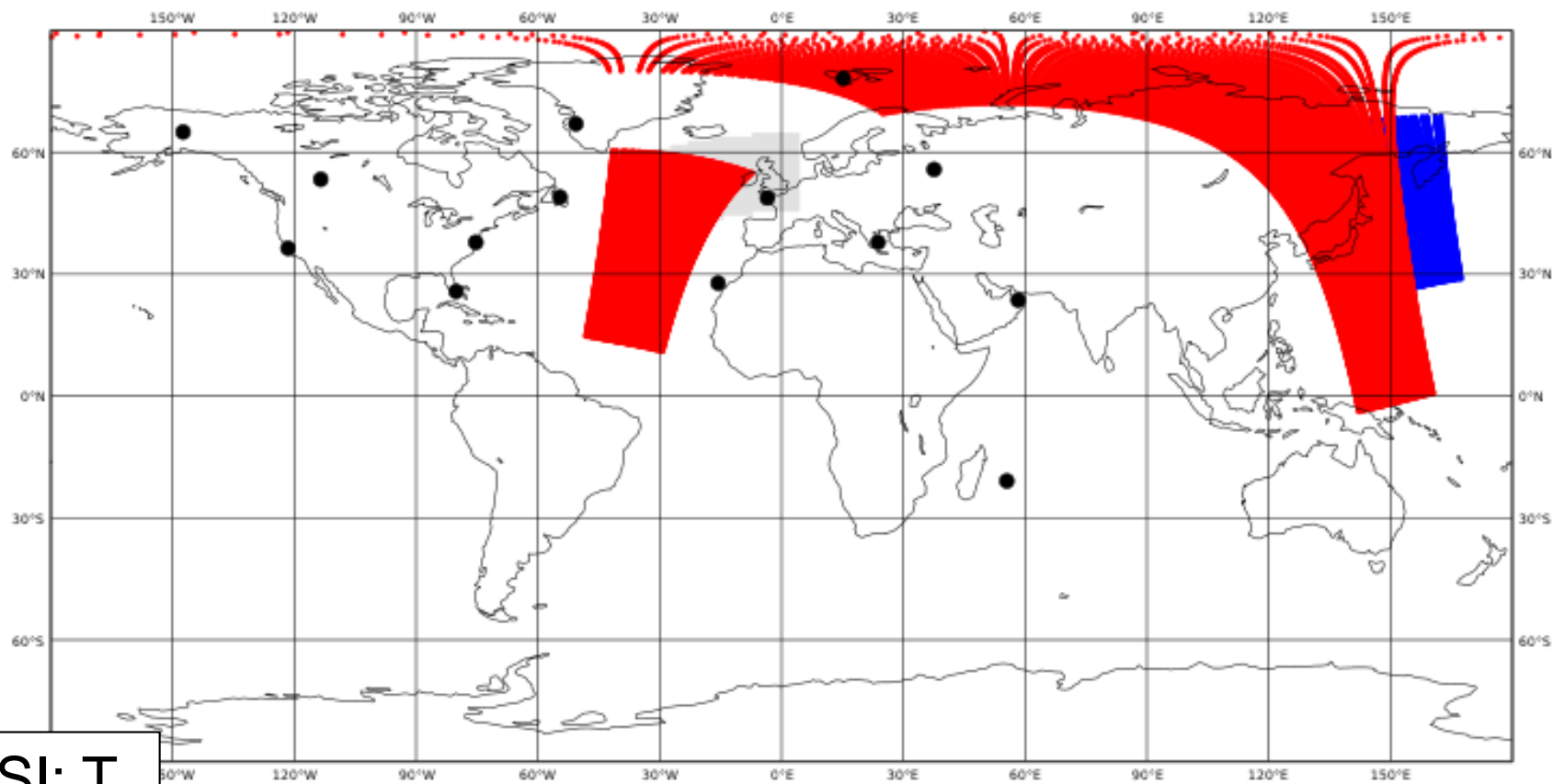
• METOP-A: 132840 • METOP-B: 92880 • NOAA-18: 23760 • NOAA-19: 175950 • NOAA-20: 0



AMSUB/MHS:  $T_b$

Data Coverage: IASI  
2019-01-24: 12UTC +/-90min  
Total number of observations: 51720

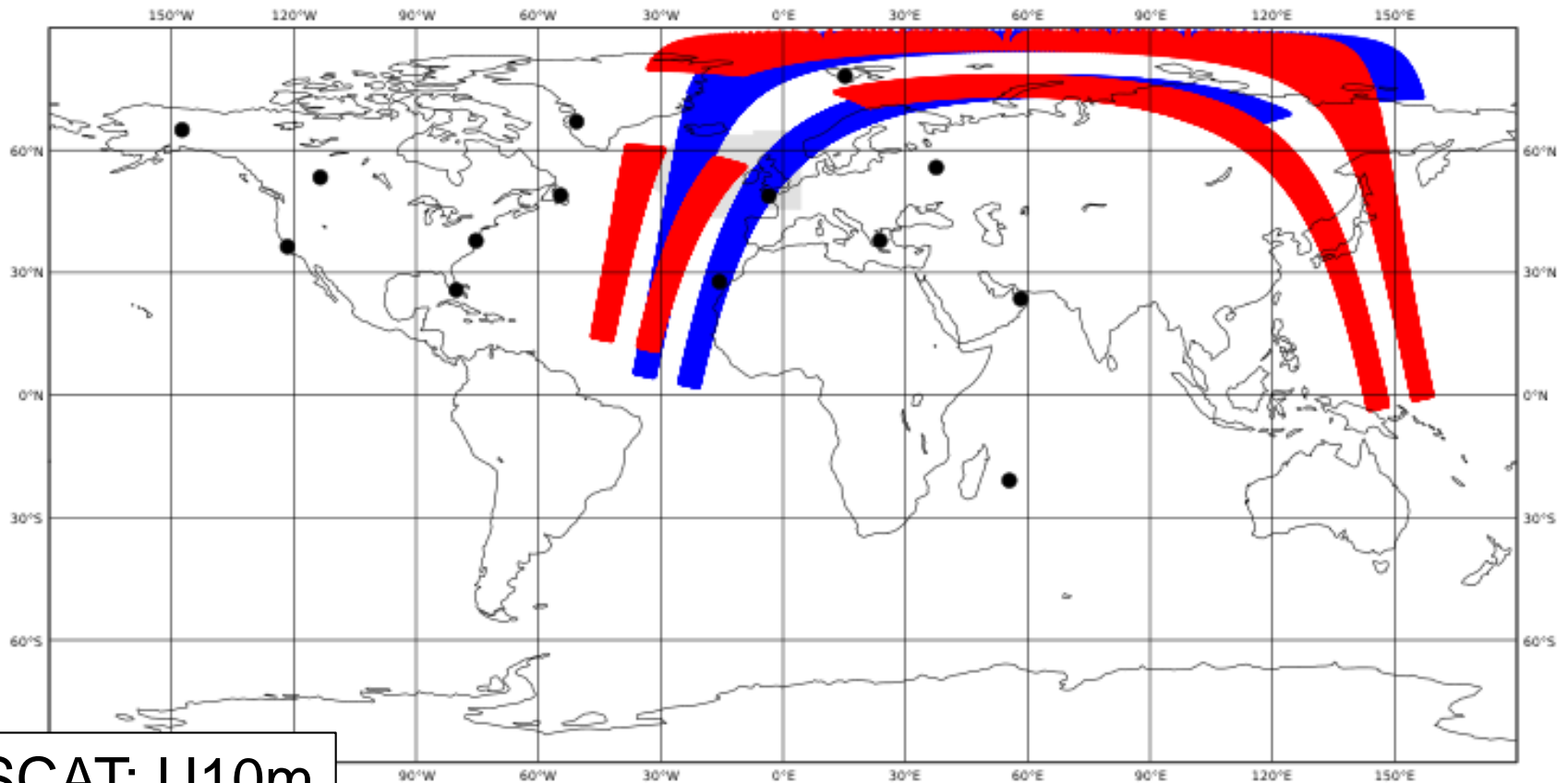
- METOP-A: 10440
- METOP-B: 41280



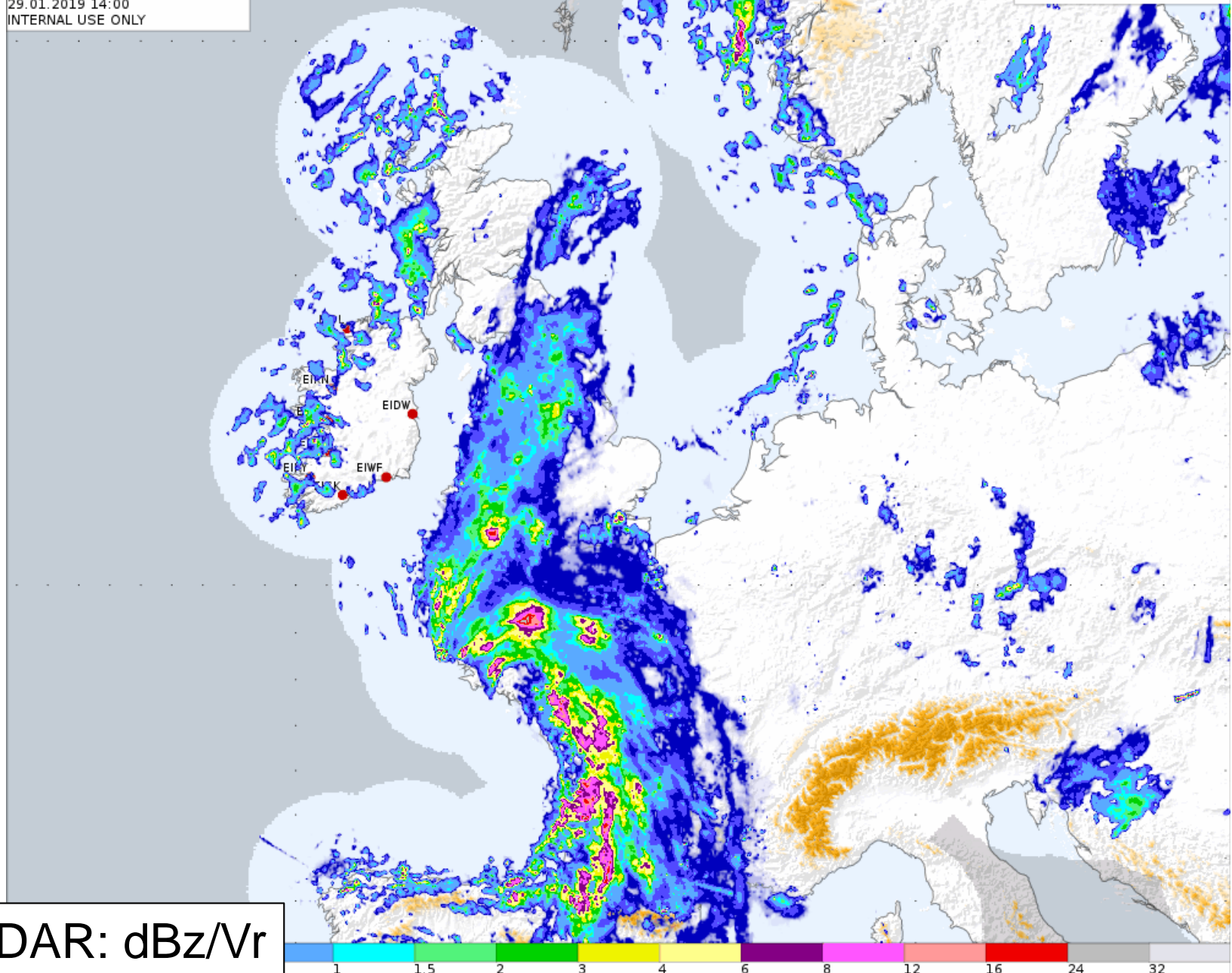
IASI: T<sub>b</sub>

Data Coverage: SCATT  
2019-01-24: 12UTC +/-90min  
Total number of observations: 256496

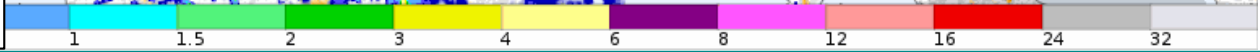
- METOP-A: 135300
- METOP-B: 121196







RADAR: dBz/Vr





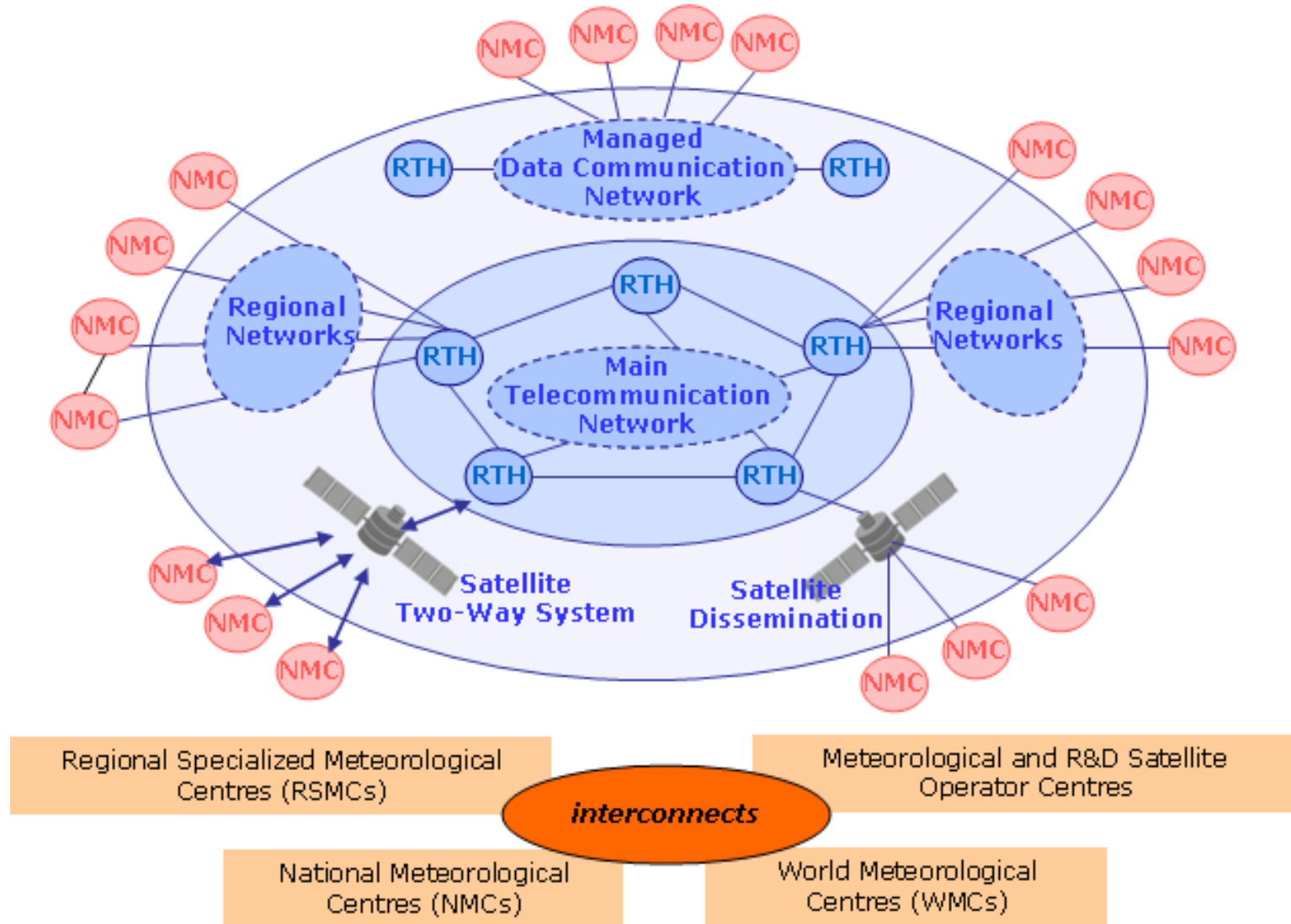
# Other observations

- Mode-S (EHS/MRAR)
  - <http://mode-s.knmi.nl/>
  - <https://www.umn-cnrm.fr/aladin/IMG/pdf/modes-bs.pptx.pdf>
  - European Meteorological Aircraft Derived Data Center (EMADDC)
- Crowd-sourced
  - Many opportunities!

# System aspects

- Data formats & data-handling tools

# Global Telecommunication System



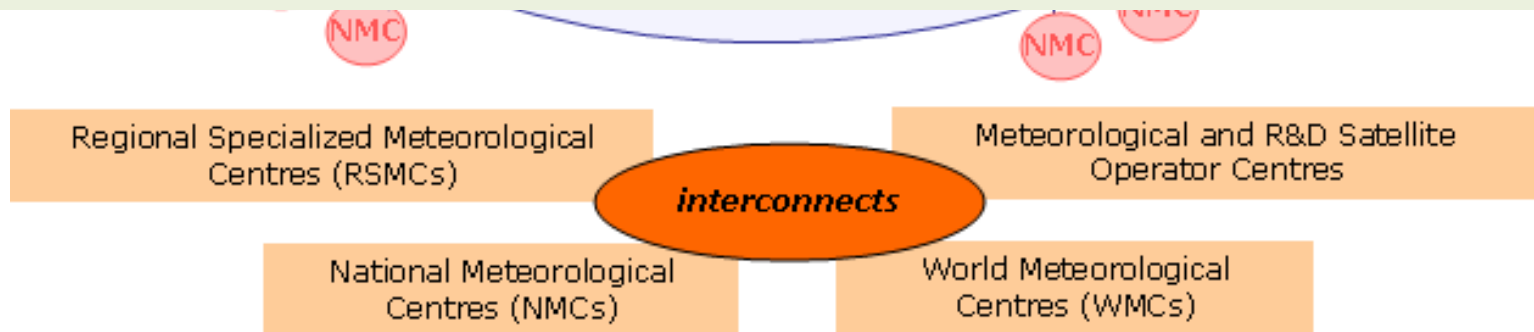
Credit: WMO, [http://www.wmo.int/pages/prog/www/TEM/GTS/index\\_en.html](http://www.wmo.int/pages/prog/www/TEM/GTS/index_en.html)



# Global Telecommunication System



"The co-ordinated global system of telecommunication facilities and arrangements for the rapid collection, exchange and distribution of observations and processed information within the framework of the World Weather Watch."



Credit: WMO, [http://www.wmo.int/pages/prog/www/TEM/GTS/index\\_en.html](http://www.wmo.int/pages/prog/www/TEM/GTS/index_en.html)

# GTS messages

- All the information you will need!
  - <http://www.wmo.int/pages/prog/www/ois/ois-home.html>
  - <https://wiswiki.wmo.int/tiki-index.php?page=ManualGTS>
  - [http://www.wmo.int/pages/prog/www/ois/Operational Information/Publications/WMO 386/AHLsymbols/AHLsymbols en.html](http://www.wmo.int/pages/prog/www/ois/Operational_Information/Publications/WMO_386/AHLsymbols/AHLsymbols_en.html)
- All the software you will need!
  - <https://confluence.ecmwf.int/display/ECC/ecCodes+Home>
  - <https://confluence.ecmwf.int/display/OPTR/ecCodes%3A+BUFR+data+decoding+and+encoding+software+2017>  
(eccodes\_bufc\_ecCodes\_extra.pdf)
  - GTS tools: gts\_ls, gts\_dump, gts\_filter
  - More in the practical session after lunch





# BUFR data

- Binary Universal Form for the Representation of Meteorological Data
- Used for non-gridded data; i.e. obs!
- All the information you will need!
  - [http://www.wmo.int/pages/prog/www/WMOCodes/WMO306\\_vI2/VolumeI.2.html](http://www.wmo.int/pages/prog/www/WMOCodes/WMO306_vI2/VolumeI.2.html)
- All the software you will need!
  - <https://confluence.ecmwf.int/display/ECC/ecCodes+Home>
  - BUFR tools: bufr\_ls, bufr\_dump, bufr\_filter
  - <https://confluence.ecmwf.int/display/METV>
  - Metview: data examiner and plotting
  - More in the practical session after lunch



# BUFR data

Section 0	"BUFR" + length of BUFR
Section 1	Data identification: category, BUFR table, date, time
Section 2	Local information: optional (used by ECMWF)
Section 3	Data description: # subsets, descriptors, compression on off
Section 4	The data!
Section 5	"7777" (end of BUFR)







# BUFR data

```
bufr_dump -p file.bufr
```

```
delayedDescriptorReplicationFactor= {1, 0, 1, 0, 1, 0, 1, 0, 1, 0, 1, 0, 2, 0, 2, 0, 2, 0, 1, 0, 2, 0, 1, 0, 2, 0}
edition=4
masterTableNumber=0
bufrHeaderCentre=233
bufrHeaderSubCentre=0
updateSequenceNumber=0
dataCategory=0
internationalDataSubCategory=2
dataSubCategory=0
masterTablesVersionNumber=14
localTablesVersionNumber=0
typicalYear=2019
typicalMonth=1
typicalDay=17
typicalHour=12
typicalMinute=0
typicalSecond=0
numberOfSubsets=12
observedData=1
compressedData=0
unexpandedDescriptors=307080
#1#blockNumber=3
#1#stationNumber=951
#1#stationOrSiteName="SHERKIN ISLAND"
#1#stationType=0
#1#year=2019
#1#month=1
#1#day=17
#1#hour=12
#1#minute=0
#1#latitude=51.47
#1#longitude=-9.42
#1#heightOfStationGroundAboveMeanSeaLevel=20
#1#heightOfBarometerAboveMeanSeaLevel=21
#1#nonCoordinatePressure=101780
:
```



# BUFR data

metview -e BUFR file.bufr

singleSYNOP.gts - Bufr Examiner (Metview)

File View Profiles Filter Help

Key profile: **nv System::Default**

File: /home/ewhelan/pCloudDrive/Dropbox/WorkLaptop/201902DACOURSE/singleSYNOP.gts  
Permissions: rw-r--r-- Owner: ewhelan Group: ewhelan Size: 2.2 KB Modified: 2019-01-30 14:13:05  
Total number of messages: 1

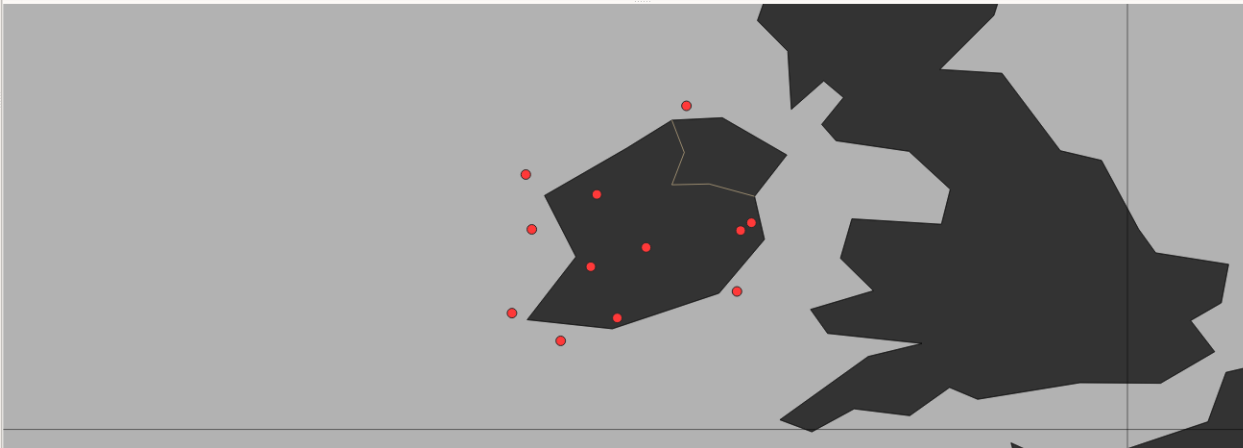
Message: **1** subsets: 12 (uncompressed) (number of messages: 1)

Message	Typ	Sut	C	Mv	Lv	Ssc	Z	D	T	ident
01	0	0	eidb	14	0	12	0	20190117	120000	N/A

Data tree Compressed Tables Debug Locations

Number of locations: 12

Message	Subset	Rank	Latitude	Longitude
1	1	1	51.4700	-9.4200
1	2	1	51.9300	-10.2300
1	3	1	51.8500	-8.4800
1	4	1	52.2900	-6.4900
1	5	1	52.7000	-8.9200
1	6	1	53.3200	-9.9000
1	7	1	53.0200	-8.0000
1	8	1	53.3000	-6.4300
1	9	1	53.4200	6.2500



Scanning locations : DONE



# BUFR data

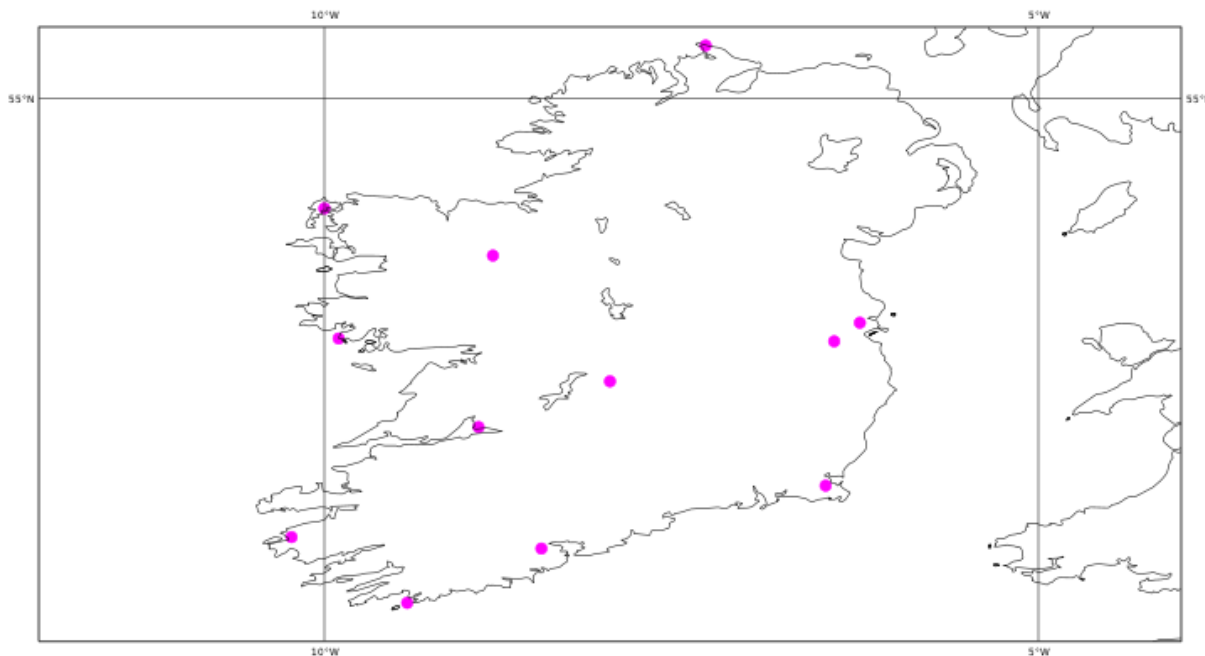
metview plotting – more later!

Data Coverage: Surface data - Land

2019-01-17: 12 UTC +/- 0min

Total number of observations: 12

● Hourly SYNOP [0]: 0



# System tools: ShuffleBufr

- Simple FORTRAN program
  - util/oulan/ShuffleBufr.F90
- Splits input BUFR file by type
- Output files readable by Bator
  - More on this from Alena

# System tools: ShuffleBufr

## PROGRAM SHUFFLEBUFR

Split and shuffle BUFR file into specific BUFR files for OULAN

Usage: SHUFFLEBUFR -i <bufr\_file> [-s1|-s2|-s3] [-a] [-r]

-s1 : Synop ship will be extracted in <synop>

-s2 : Synop ship will be extracted in <buoy>

-s3 : Synop ship will be extracted in <ship>

Nota Bene: If -s1,-s2 or -s3 are not specified  
synop\_ship will not be extracted

-a : Extracts ATOVS in files amsua and amsub

-r : Extracts also record messages (synop)

# System tools: ShuffleBufr

- Bator expects input BUFR files
- BUFR files split by observation type
- Names match Bator (BUFR) type names
  - src/odb/pandor/module/bator\_init\_mod.F90
- For conventional:
  - synop
  - buoy,moored,drift
  - temp,temps
  - airep/amdar
  - gpssol
  - modes

# Miscellany: Local GTS processing

- Monitoring
- Decoding & re-coding (for NWP)
- Duplicate/correction handling
- Gross-error checking
- Other simple QC  
(consistency/integrity)





# Miscellany: Local GTS processing

- ECMWF: SAPP & MARS
  - <https://confluence.ecmwf.int/display/UDOC/MARS+user+documentation>
  - <https://www.ecmwf.int/en/elibrary/17341-sapp-new-scalable-acquisition-and-pre-processing-system-ecmwf>
- Météo France: BDMO
  - <http://www.umr-cnrm.fr/gmapdoc/spip.php?article226>
- RC LACE: OPLACE
  - <https://meetingorganizer.copernicus.org/EMS2018/EMS2018-837.pdf>
- Everybody else!



# Miscellany: possible developments

- SAPP
  - Scalable Acquisition and PreProcessing
  - System available as ECMWF Optional Programme
- COPE
  - Continuous Observation Preprocessing Environment
  - Flexible software to process observations for NWP
  - Reads BUFR/ODB-2
  - Writes ODB-2
- ODB-API & ODB-2
  - Software & format to handle observation and observation feedback information
  - <https://confluence.ecmwf.int/display/ODBAPI>



